

What is...quantum topology - part 28?

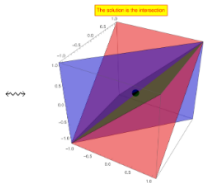
Or: Additive categories 1 from Chapter 6

Why addition enters the story

The art of solving linear equations

$$\begin{cases} 0x + 1/2y - 1/2z = 0 & \text{(Red)} \\ -1/2x + 0y + 1/2z = 0 & \text{(Green)} \\ 1/2x - 1/2y + 0z = 0 & \text{(Blue)} \end{cases}$$

or equivalently

$$\left(\begin{array}{ccc|c} 0 & 1/2 & -1/2 & 0 \\ -1/2 & 0 & 1/2 & 0 \\ 1/2 & -1/2 & 0 & 0 \end{array} \right)$$


The need for a **machine** to solve linear equations grew out of...

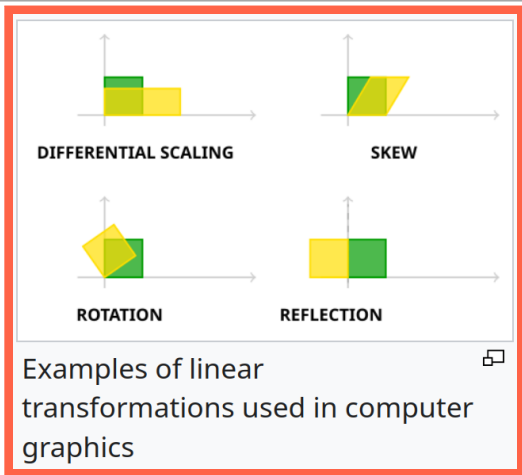
- ▶ ...Cartesian geometry
- ▶ ...the geometry of lines, planes and hyperplanes
- ▶ ...that solving other types of equations (polynomial or even worse) is very hard

Linear algebra provides **algorithms** to solve linear problems

FIGURE 12. The essence of linear algebra.

- ▶ Braiding etc. gave us a way to read **diagrams**
- ▶ But invariants should also be **computable**
- ▶ So we need to add the categorical version of **linear algebra**

Adding morphisms



- ▶ Between two vector spaces, maps themselves form a vector space
- ▶ This means we can add maps, subtract maps and use a zero map
- ▶ An additive category remembers exactly this bookkeeping of arrows

Zero objects and direct sums

Finally, we consider the pair category (see Definition 1B.12) $\mathbf{Vec}_k \times \mathbf{Vec}_k$ and we have a bifunctor

$$\oplus: \mathbf{Vec}_k \times \mathbf{Vec}_k \rightarrow \mathbf{Vec}_k, \quad \oplus((X, Y)) = X \oplus Y, \quad \oplus((f, g)) = f \oplus g,$$

called the *direct sum*, using again abbreviations of the form $X \oplus Y$ instead of $\oplus((X, Y))$. We note that the object $X \oplus Y$ has a universal-type property, namely: there exist morphisms $i_X, i_Y, p_X, p_Y \in \mathbf{Vec}_k$ such that

$$(6B-3) \quad \begin{array}{ccc} & X \oplus Y & \\ i_X \nearrow & & \nwarrow i_Y \\ X & & Y \\ p_X \searrow & & \swarrow p_Y \end{array}, \quad p_X i_X = \text{id}_X, \quad p_Y i_Y = \text{id}_Y, \quad i_X p_X + i_Y p_Y = \text{id}_{X \oplus Y}.$$

The two morphisms i_X and i_Y are called *inclusions*, the other two p_X and p_Y *projections* (of X and Y , respectively).

- ▶ The zero object is the categorical version of **nothing to see here**
- ▶ A direct sum puts two objects side by side without forcing them to **interact**
- ▶ Inclusions and projections are the **handles** for moving in and out; the abstract definition is above

Matrices already know this

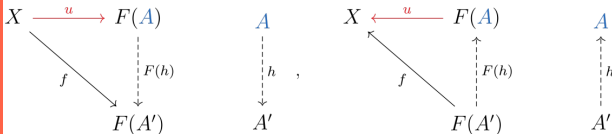
$$A \oplus B = \begin{bmatrix} a_{11} & \cdots & a_{1n} & 0 & \cdots & 0 \\ \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} & 0 & \cdots & 0 \\ 0 & \cdots & 0 & b_{11} & \cdots & b_{1q} \\ \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ 0 & \cdots & 0 & b_{p1} & \cdots & b_{pq} \end{bmatrix}$$

- ▶ Matrix addition is the most down-to-earth **model example**
- ▶ Block matrices are direct sums wearing a **very visible costume**
- ▶ The abstract definitions only package what matrices have done **all along**

The universal-property mindset

For completeness: A formal definition

- ▶ $F: C \rightarrow D$, $X \in D$, a universal morphism from X to F is a pair $(A, u: X \rightarrow F(A))$ such that $\exists! h$ making the left diagram below commute
- ▶ $F: C \rightarrow D$, $X \in D$, a universal morphism from F to X is a pair $(A, u: F(A) \rightarrow X)$ such that $\exists! h$ making the right diagram below commute



- ▶ These might not exist
- ▶ If they exist, then they are unique up to unique isomorphism

- ▶ We often define objects by what they do, not by how they are built
- ▶ This is why direct sums are controlled by maps in and maps out
- ▶ Reward = uniqueness up to unique isomorphism = as canonical as it gets

Thank you for your attention!